

# Optimal Policy with Endogenous Signal Extraction

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# Motivation

- ▶ Policy is generally conducted under uncertainty, based on some aggregate variables that are endogenous with respect to policy decisions.
- ▶ Example: Fiscal policy reaction to the Great Recession
  - ▶ Economist A says it is a permanent decrease in the productive capacity of the economy
  - ▶ Economist B says it is a temporary fall in demand
  - ▶ All we knew for sure in 2008/09 was that employment, output, etc were low
  - ▶ Policy-makers must decide what to do based on these aggregate variables, which in turn are affected by policy.
- ▶ What is the optimal way to choose policy, contingent on **endogenous partial information**?

# Our contribution

- ▶ We solve for the optimal policy in models with multidimensional uncertainty and endogenous observables
- ▶ Key issue: Endogeneity of the distribution of observables. We need to jointly estimate the state and optimize (endogenous filtering problem)
- ▶ Application: Optimal fiscal policy is very non-linear: tax smoothing in normal times, but large precautionary adjustments in downturns in economies with high  $g$  or high debt
- ▶ Policies based on averages of Full Information can be quite wrong

## Signal extraction, exogenous shocks

- ▶ transitory/permanent exogenous shocks  
Muth (1960) ...
- ▶ idem for competitive agents observing prices under private information  
Lucas's (1972)  
Townsend (1983)  
Guerrieri and Shimer (2013)  
Angeletos and Pavan (2010)

# Armed-Bandit problems

Endogenous fabrication of signal information, but given signal choose policy

Kiefer and Nyarko (1989)

Wieland (2000a, 2000b)

Ellison and Valla (2001)

Mirmann, Samuelson and Urbano (1993)

# Linear Endogenous Signal extraction

Endogenous signal extraction does not influence FOC of optimality

Pearlman (1992)

Pearlman and Levine (2013)

Svensson and Woodford (2003, 2004)

Nimark (2008)

# Private Info, Incentive compatibility

Agents understand how their reported signal influences principal's action

Kocherlakota, Golosov, Tsyvinski.

# Many applications

- ▶ Monetary policy
- ▶ Macro-prudential policy
- ▶ Monopolist under partial info
  - Fiscal Policy(today)
  - Automatic Stabilizers



# A simple model of optimal fiscal policy

- ▶ Optimal policy under uncertainty (2-period version of Lucas & Stokey, 1983), with multidimensional private information and incomplete markets
- ▶ Gov't needs to finance  $(g_1, g_2)$  with distortionary taxes and debt  $(\tau_1, \tau_2, b)$
- ▶ Continuum of atomistic identical agents with utility function

$$U(c_1, l_1, c_2, l_2) = \gamma u(c_1) - v(l_1) + \beta [u(c_2) - v(l_2)].$$

with  $u' > 0$ ,  $u'' < 0$ ,  $v' > 0$ ,  $v'' > 0$ .

- ▶  $\gamma \sim F_\gamma$  is a temporary preference shock, or demand shock

## Consumers (cont'd)

- ▶ Period budget constraints

$$c_1 + qb = \theta_1 h_1 (1 - \tau_1)$$

$$c_2 = \theta_2 h_2 (1 - \tau_2) + b$$

- ▶  $\theta_1 = \theta_2 = \theta \sim F_\theta$  is permanent productivity shock
- ▶  $(\theta, \gamma)$  is observed by the agent at  $t = 1$
- ▶ Consumption-leisure margin for  $t = 1, 2$

$$\frac{v'(h_1)}{u'(c_1)} = \theta \gamma (1 - \tau_1)$$

$$\frac{v'(h_2)}{u'(c_2)} = \theta (1 - \tau_2)$$

- ▶ Euler equation for gov't bonds

$$q_1 = \beta \frac{u'(c_2)}{\gamma u'(c_1)}$$

## Reaction function

The consumption-leisure margin, combined with the resource constraint  $c_t + g_t = \theta l_t$  for  $t = 1$ , gives a reaction function

$$l_1 = h(\tau_1, \theta, \gamma)$$

Example with simple analytical solutions:

$$u(c) = c \quad v(l) = B \frac{l^2}{2}$$

We get

$$q = \frac{\beta}{\gamma}$$

$$l_1 = h(\tau_1, \theta, \gamma) = \frac{\gamma \theta}{B} (1 - \tau_1)$$

## Ramsey problem with Full Information

- ▶ A Ramsey government chooses a policy  $(\tau_1, \tau_2, b)$  to maximize  $U(c_1, l_1, c_2, l_2)$  subject to competitive equilibrium
- ▶ Substituting all the constraints in  $U$ , we can write the problem as a choice of  $\tau_1$  in order to maximize

$$\mathbb{E}W(l_1; \theta, \gamma)$$

subject to  $l_1 = h(\tau_1, \theta, \gamma)$

- ▶ If the gov't observes  $(\theta, \gamma)$ , set

$$W_l(l_1^{FI}(\theta, \gamma); \theta, \gamma) = 0$$

- ▶ and invert  $h$  to get  $\tau_1^{FI}(\theta, \gamma)$ . This will imply tax-smoothing over time.

## Ramsey problem with Invertibility (1 shock, 1 observable)

- ▶  $\gamma = 1$  and only  $\theta$  random and private information to the agent, observed by the gov't only in the second period.
- ▶ Gov't can commit to a policy conditional only on  $l_1$
- ▶ Only apparently a private information problem: if  $h(\tau_1^{FI}(\theta, 1), \theta, 1)$  is invertible with respect to  $\theta$ , observing  $l_1$  is the same as observing  $\theta$ , so that the gov't can implement the Full Information policy.

## Ramsey problem with Partial Information (2 shocks, 1 observable)

- ▶ Now  $(\theta, \gamma)$  random and private information to the agent, observed by the gov't only in the second period (together with  $c_1, q, b$ ).
- ▶ Gov't can commit to a policy  $\tau_1 = \mathcal{R}(l_1)$
- ▶ An equilibrium  $(l_1^{PI}(\theta, \gamma), \tau_1^{PI}(\theta, \gamma))$  is the intersection of the policy function with the agent's reaction function

$$l_1 = h(\tau_1, \theta, \gamma)$$

- ▶ Key issue: condition on  $l$ ,  $F_l(l; \mathcal{R})$  endogenous
- ▶ Uncertainty about revenue  $\tau_1 \theta l_1$

# Endogenous signal extraction

$f_{A|I}$  depends on  $\mathcal{R}$ :

$I$  given implicitly by

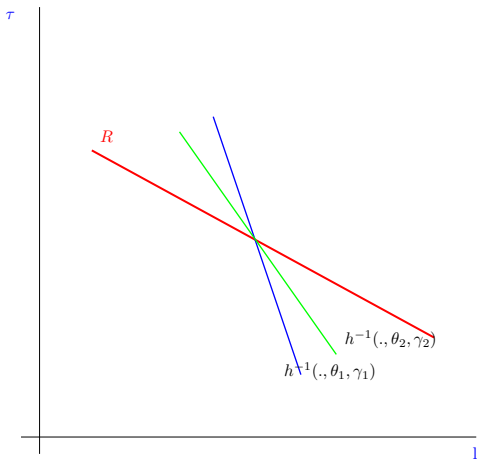
$$I = h_{\tau}(\mathcal{R}(I), \gamma, \theta)$$

so  $I$  as a function of  $A = (\gamma, \theta)$  depends on  $\mathcal{R}$ .

So  $f_{I|A}$  depends on  $\mathcal{R}$  (change rule).

$f_{A|I}$  depends on  $f_{I|A}$  (Bayes' rule), so it depends on  $\mathcal{R}$

# No invertibility





# Optimal Policy

- ▶  $H(l_1, \theta, \gamma) \equiv l_1 - h(\mathcal{R}(l_1), \theta, \gamma) = 0$  at the equilibrium implied by a policy  $\mathcal{R}$ 
  - ▶ This defines implicitly  $l_1 = L(\theta, \gamma; \mathcal{R})$
  - ▶ and its inverse  $\gamma = \tilde{\gamma}(\theta, l_1; \mathcal{R})$

$$\frac{dE(W(L(\mathcal{R}^* + \alpha\delta, A)))}{d\alpha} = 0$$
$$E\left(W_l(L(\mathcal{R}^* + \alpha\delta, A)) \frac{dL(\mathcal{R}^* + \alpha\delta, A)}{d\alpha}\right) = 0$$

## Step 2: Derivative of L

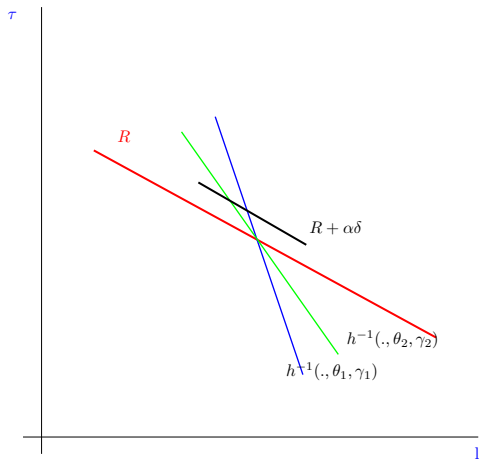
By the implicit function theorem applied on  $H(l_1, \theta, \gamma)$ , get

$$\frac{dL_1(\theta, \gamma; \mathcal{R}^* + \alpha\delta)}{d\alpha} \Big|_{\alpha=0} = \frac{\delta(L_1(\theta, \gamma; \mathcal{R}^*))h_\tau}{1 - h_\tau \mathcal{R}^{*'}}$$

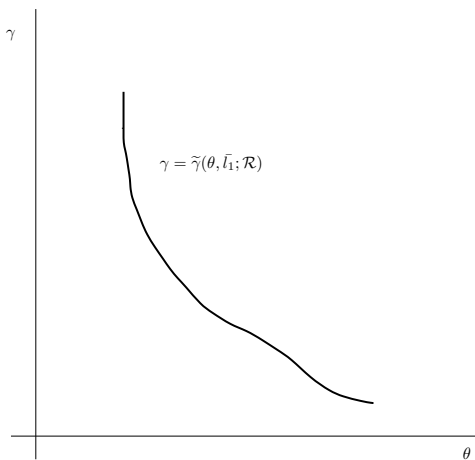
Take the deviation  $\delta$  to be the indicator function for a set  $(\bar{l}_1 - \varepsilon, \bar{l}_1 + \varepsilon)$  and take the limit  $\varepsilon \rightarrow 0$ , to get

$$E(W_l \frac{h_\tau}{1 - h_\tau \mathcal{R}^{*'}} | \bar{l}_1) = 0$$

# Deviation



# Locus of shocks realizations conditional on $l$



When is the kernel irrelevant?

$$\frac{h_{\tau}(\mathcal{R}(l), \gamma, \theta)}{1 - \mathcal{R}'(l)h_{\tau}(\mathcal{R}(l), \gamma, \theta)}$$

When is this non-random conditional on  $l$ ?

- ▶ If  $(\gamma, \theta)$  is known given  $\tau, l$
- ▶ If  $h_{\tau}(\mathcal{R}(l), \gamma, \theta)$  non-random
  - ▶ signal  $l = h(\tau, \gamma, \theta)$  does not depend on  $\tau$
  - ▶  $h$  linear in  $\tau$

## Back to the example

Numerical algorithm:

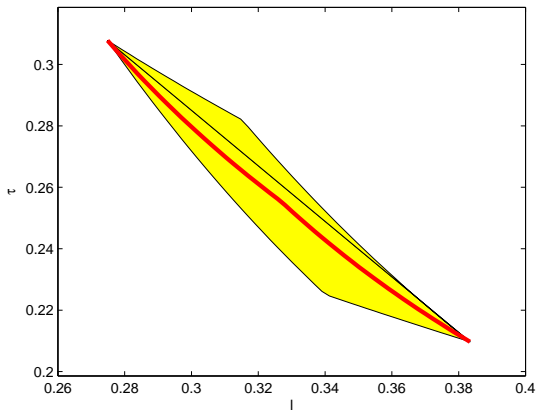
- ▶ Discretize support of shocks and support of  $l_1$
- ▶ Iterate to find a fixed point of the mapping between
  - ▶ a policy  $\mathcal{R}$  that solves FOC at each  $l_1$  for a given conditional distribution and
  - ▶ the conditional distribution of the shocks consistent with  $\mathcal{R}$  at each  $l_1$

$\theta$  uniform on  $[\theta_{\min}, \theta_{\max}]$ ,  $\gamma$  uniform on  $[\gamma_{\min}, \gamma_{\max}]$

$$l_1 = h(\tau_1, \theta, \gamma) = \frac{\gamma\theta}{B}(1 - \tau_1)$$

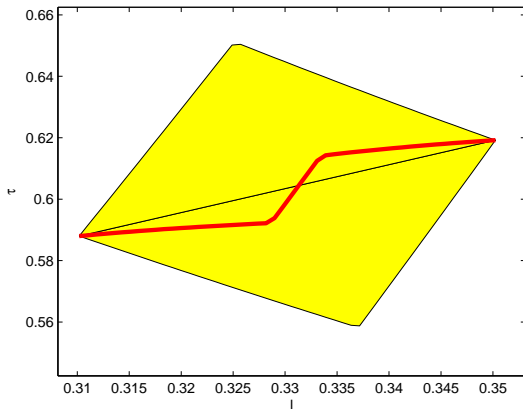
$$h_{\tau} = -\frac{\gamma\theta}{B}; h_{\gamma} = \frac{\theta(1 - \tau_1)}{B}$$

# PI v FI

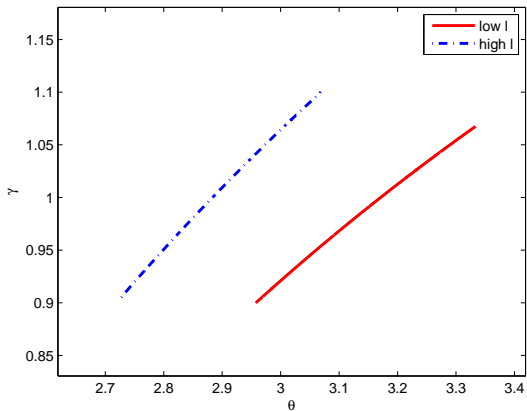




## Getting closer to the top of the Laffer curve...



# Admissible realizations



## $\infty$ -horizon model with debt

Household:

$$\mathbb{E}_0 \sum_{t=0}^{\infty} \beta^t [\gamma_t c_t - v(l_t)]$$

$$c_t + q_t b_t = \theta_t l_t (1 - \tau_t) + b_{t-1}$$

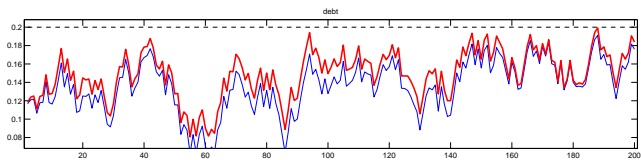
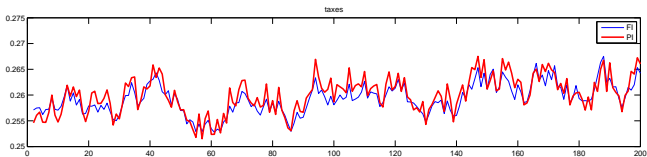
$\theta_t, \gamma_t$  i.i.d. shocks

Government:

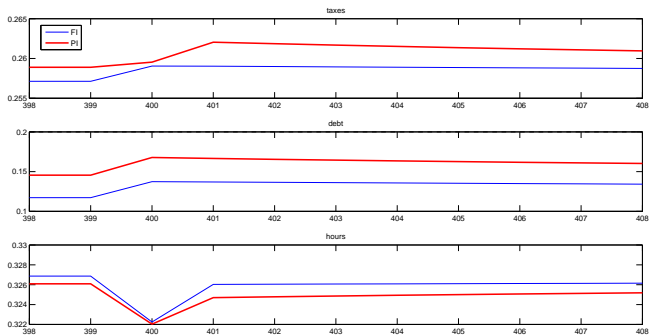
$$\tau_t = \mathcal{R}(b_{t-1}, l_t)$$

$$b_t \leq \bar{b}$$

# Simulation



# Delayed fiscal response and prolonged recession



# Summing up

- ▶ With Partial Information, gov't averages the Full Information first order conditions, with weights that depend on
  - ▶ How responsive endogenous observables are to policy
  - ▶ The interaction between the shocks
- ▶ With low expenditure/debt, taxes are smooth
- ▶ When expenditure/debt is high
  - ▶ The gov't may have to react a lot to observables
  - ▶ The endogeneity of observables matters

# The game

- ▶ Gov't chooses  $\mathcal{R}$ , taking into account how the reaction  $h$  will be formulated
- ▶  $(\theta, \gamma)$  is realised, and observed only by the agent
- ▶ The agent chooses  $h$
- ▶ The equilibrium is realised at the intersection of  $\mathcal{R}$  and  $h$

## Log-quadratic example

$$l_1 = h(\tau_1, \theta, \gamma) = \frac{Bg_1 + \sqrt{(Bg_1)^2 + 4B\theta^2\gamma(1-\tau)}}{2B\theta}$$

$$h_\tau = \frac{-\theta\gamma}{\sqrt{(Bg_1)^2 + 4B\theta^2\gamma(1-\tau)}}; h_\gamma = \frac{\theta(1-\tau)}{\sqrt{(Bg_1)^2 + 4B\theta^2\gamma(1-\tau)}}$$



# New-Keynesian monetary policy model with Partial Information

Reaction function derived from:

$$x_t = \mathbb{E}_t x_{t+1} - \phi(i_t - E_t \pi_{t+1}) + g_t$$

$$\pi_t = \beta E_t \pi_{t+1} + \lambda x_t + u_t$$

Policy:

$$i_t = \mathcal{R}(\pi_t)$$